

# Cosmology in generalized hybrid metric-Palatini gravity

João Luís Rosa

Universidade de Lisboa - Instituto Superior Técnico

2nd IDPASC Student's Workshop 2016, FEUP

*joaoluis92@gmail.com*

June 23, 2016

## 1 Motivation

## 2 Formalism

- Action and field equations
- Scalar-tensor representation

## 3 Cosmological Dynamics

- FLRW universes
- Accelerating models

## 4 Conclusions

**Fact:** Universe is expanding at an accelerated rate.[1, 2]

Cosmological constant ( $\Lambda$ ) vs. Modified gravity[3, 4, 5]

Hybrid metric-Palatini gravity[6, 7]:

- 1 Passes the solar system observational constraints;
- 2 Long range scalar field modifies cosmological dynamics;
- 3 Stable against perturbations.

Next step: **Generalized** hybrid metric-Palatini gravity[8]

$$\mathcal{L}_H = \frac{\sqrt{-g}}{2\kappa^2} [R + f(\mathcal{R})] \quad \rightarrow \quad \mathcal{L}_{GH} = \frac{\sqrt{-g}}{2\kappa^2} f(R, \mathcal{R}). \quad (1)$$

# Action and field equations

Generalized hybrid metric-Palatini gravity:

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} f(R, \mathcal{R}) d^4x + S_m, \quad (2)$$

$$\mathcal{R} \equiv g_{ab} \mathcal{R}^{ab}, \quad \mathcal{R}_{ab} = \partial_c \hat{\Gamma}_{ab}^c - \partial_b \hat{\Gamma}_{ac}^c + \hat{\Gamma}_{cd}^c \hat{\Gamma}_{ab}^d - \hat{\Gamma}_{ad}^c \hat{\Gamma}_{cb}^d. \quad (3)$$

# Action and field equations

Generalized hybrid metric-Palatini gravity:

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} f(R, \mathcal{R}) d^4x + S_m, \quad (2)$$

$$\mathcal{R} \equiv g_{ab} \mathcal{R}^{ab}, \quad \mathcal{R}_{ab} = \partial_c \hat{\Gamma}_{ab}^c - \partial_b \hat{\Gamma}_{ac}^c + \hat{\Gamma}_{cd}^c \hat{\Gamma}_{ab}^d - \hat{\Gamma}_{ad}^c \hat{\Gamma}_{cb}^d. \quad (3)$$

Applying the variational method with respect to  $\hat{\Gamma}$

$$\hat{\nabla}_c \left( \sqrt{-g} \frac{\partial f}{\partial \mathcal{R}} g^{ab} \right) = 0. \quad (4)$$

Implies that it exists a new metric  $h_{ab} = g_{ab} \partial f / \partial \mathcal{R}$  such that

$$\hat{\Gamma}_{bc}^a = \frac{1}{2} h^{ad} (\partial_b h_{dc} + \partial_c h_{bd} - \partial_d h_{bc}). \quad (5)$$

# Action and field equations

Generalized hybrid metric-Palatini gravity:

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} f(R, \mathcal{R}) d^4x + S_m, \quad (2)$$

$$\mathcal{R} \equiv g_{ab} \mathcal{R}^{ab}, \quad \mathcal{R}_{ab} = \partial_c \hat{\Gamma}_{ab}^c - \partial_b \hat{\Gamma}_{ac}^c + \hat{\Gamma}_{cd}^c \hat{\Gamma}_{ab}^d - \hat{\Gamma}_{ad}^c \hat{\Gamma}_{cb}^d. \quad (3)$$

Applying the variational method with respect to  $\hat{\Gamma}$

$$\hat{\nabla}_c \left( \sqrt{-g} \frac{\partial f}{\partial \mathcal{R}} g^{ab} \right) = 0. \quad (4)$$

Implies that it exists a new metric  $h_{ab} = g_{ab} \partial f / \partial \mathcal{R}$  such that

$$\hat{\Gamma}_{bc}^a = \frac{1}{2} h^{ad} (\partial_b h_{dc} + \partial_c h_{bd} - \partial_d h_{bc}). \quad (5)$$

The field equations in this theory are

$$\frac{\partial f}{\partial R} R_{ab} + \frac{\partial f}{\partial \mathcal{R}} \mathcal{R}_{ab} - \frac{1}{2} g_{ab} f(R, \mathcal{R}) - (\nabla_a \nabla_b - g_{ab} \square) \frac{\partial f}{\partial R} = \kappa^2 T_{ab}. \quad (6)$$

# Scalar-tensor representation

Adding two auxiliary fields  $\alpha$  and  $\beta$  to the action

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ f(\alpha, \beta) + \frac{\partial f}{\partial \alpha} (R - \alpha) + \frac{\partial f}{\partial \beta} (\mathcal{R} - \beta) \right] d^4x. \quad (7)$$

# Scalar-tensor representation

Adding two auxiliary fields  $\alpha$  and  $\beta$  to the action

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ f(\alpha, \beta) + \frac{\partial f}{\partial \alpha} (R - \alpha) + \frac{\partial f}{\partial \beta} (\mathcal{R} - \beta) \right] d^4x. \quad (7)$$

Using  $\alpha = R$  and  $\beta = \mathcal{R}$  we recover the original action. Defining:

$$\varphi = \frac{\partial f}{\partial \alpha} \quad \psi = -\frac{\partial f}{\partial \beta} \quad (8)$$

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} [\varphi R - \psi \mathcal{R} - V(\varphi, \psi)] d^4x, \quad (9)$$

$$V(\varphi, \psi) = -f(\alpha, \beta) + \varphi \alpha - \psi \beta. \quad (10)$$



# Scalar-tensor representation

Adding two auxiliary fields  $\alpha$  and  $\beta$  to the action

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ f(\alpha, \beta) + \frac{\partial f}{\partial \alpha} (R - \alpha) + \frac{\partial f}{\partial \beta} (\mathcal{R} - \beta) \right] d^4x. \quad (7)$$

Using  $\alpha = R$  and  $\beta = \mathcal{R}$  we recover the original action. Defining:

$$\varphi = \frac{\partial f}{\partial \alpha} \quad \psi = -\frac{\partial f}{\partial \beta} \quad (8)$$

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} [\varphi R - \psi \mathcal{R} - V(\varphi, \psi)] d^4x, \quad (9)$$

$$V(\varphi, \psi) = -f(\alpha, \beta) + \varphi \alpha - \psi \beta. \quad (10)$$

The relation between the Ricci tensors is given by

$$\mathcal{R} = R + \frac{3}{\psi^2} \partial^a \psi \partial_a \psi - \frac{3}{\psi} \square \psi. \quad (11)$$

# Scalar-tensor representation

The action in the form of a scalar-tensor action becomes

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ (\varphi - \psi) R - \frac{3}{2\psi} \partial^a \psi \partial_a \psi - V(\phi, \psi) \right] d^4x. \quad (12)$$

# Scalar-tensor representation

The action in the form of a scalar-tensor action becomes

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ (\varphi - \psi) R - \frac{3}{2\psi} \partial^a \psi \partial_a \psi - V(\phi, \psi) \right] d^4x. \quad (12)$$

Applying the variational method, the equations of motion are

$$\begin{aligned} (\varphi - \psi) G_{ab} = \kappa^2 T_{ab} + \frac{3}{2\psi} \partial_a \psi \partial_b \psi + \nabla_a \nabla_b (\varphi - \psi) - \\ - \left( \square (\varphi - \psi) + \frac{1}{2} V + \frac{3}{4\psi} \partial^c \psi \partial_c \psi \right) g_{ab}; \end{aligned} \quad (13)$$

# Scalar-tensor representation

The action in the form of a scalar-tensor action becomes

$$S = \frac{1}{2\kappa^2} \int_{\Omega} \sqrt{-g} \left[ (\varphi - \psi) R - \frac{3}{2\psi} \partial^a \psi \partial_a \psi - V(\phi, \psi) \right] d^4x. \quad (12)$$

Applying the variational method, the equations of motion are

$$\begin{aligned} (\varphi - \psi) G_{ab} = \kappa^2 T_{ab} + \frac{3}{2\psi} \partial_a \psi \partial_b \psi + \nabla_a \nabla_b (\varphi - \psi) - \\ - \left( \square(\varphi - \psi) + \frac{1}{2} V + \frac{3}{4\psi} \partial^c \psi \partial_c \psi \right) g_{ab}; \end{aligned} \quad (13)$$

$$\square\psi - \frac{1}{2\psi} \partial^a \psi \partial_a \psi - \frac{1}{3} (V_{\varphi} + V_{\psi}) = 0; \quad (14)$$

$$\square\varphi + \frac{1}{3} [2V - (\varphi - \psi + 1) V_{\varphi} - V_{\psi}] = \frac{\kappa^2 T}{3}. \quad (15)$$

Friedmann-Lemaître-Robertson-Walker (FLRW) line element:

$$ds^2 = -dt^2 + a^2(t) \left[ \frac{dr^2}{1 - kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right] \quad (16)$$

Friedmann-Lemaître-Robertson-Walker (FLRW) line element:

$$ds^2 = -dt^2 + a^2(t) \left[ \frac{dr^2}{1 - kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right] \quad (16)$$

Friedmann equations:

$$3 \left( H^2 + \frac{k}{a^2} \right) = \frac{1}{\varphi - \psi} \left[ \kappa^2 \rho + \frac{V}{2} + 3 \left( \frac{\dot{\psi}^2}{4\psi} - H(\dot{\varphi} - \dot{\psi}) \right) \right], \quad (17)$$

$$2 \left( \dot{H} - \frac{k}{a^2} \right) = \frac{1}{\varphi - \psi} \left[ -\kappa^2 (\rho + p) - \frac{3\dot{\psi}^2}{2\psi} + H(\dot{\varphi} - \dot{\psi}) - (\ddot{\varphi} - \ddot{\psi}) \right]; \quad (18)$$

Friedmann-Lemaître-Robertson-Walker (FLRW) line element:

$$ds^2 = -dt^2 + a^2(t) \left[ \frac{dr^2}{1 - kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right] \quad (16)$$

Friedmann equations:

$$3 \left( H^2 + \frac{k}{a^2} \right) = \frac{1}{\varphi - \psi} \left[ \kappa^2 \rho + \frac{V}{2} + 3 \left( \frac{\dot{\psi}^2}{4\psi} - H(\dot{\varphi} - \dot{\psi}) \right) \right], \quad (17)$$

$$2 \left( \dot{H} - \frac{k}{a^2} \right) = \frac{1}{\varphi - \psi} \left[ -\kappa^2(\rho + p) - \frac{3\dot{\psi}^2}{2\psi} + H(\dot{\varphi} - \dot{\psi}) - (\ddot{\varphi} - \ddot{\psi}) \right]; \quad (18)$$

Klein-Gordon equations:

$$\ddot{\psi} + 3H\dot{\psi} - \frac{\dot{\psi}^2}{2\psi} + \frac{\psi}{3} (V_\varphi + V_\psi) = 0, \quad (19)$$

$$\ddot{\varphi} + 3H\dot{\varphi} - \frac{1}{3} [2V - (\varphi - \psi + 1) V_\varphi - V_\psi] = \frac{\kappa^2}{3} (\rho - 3p). \quad (20)$$

# Accelerating models

Variable transformation:  $x = \log a$ , which implies that  $\dot{x} = \dot{a}/a = H$ .

$$\frac{d}{dt} = H \frac{d}{dx} \quad \frac{d^2}{dt^2} = \dot{H} \frac{d}{dx} + H^2 \frac{d^2}{dx^2} \quad (21)$$

$$\psi_{xx} + \left( \frac{\dot{H}}{H^2} + 3 \right) \psi_x - \frac{\psi_x^2}{2\psi} + \frac{1}{3H^2} (V_\varphi + V_\psi) = 0; \quad (22)$$

$$\varphi_{xx} + \left( \frac{\dot{H}}{H^2} + 3 \right) \varphi_x - \frac{1}{3H^2} [2V - (\varphi - \psi + 1) V_\varphi - V_\psi] = \frac{\kappa^2}{3H^2} (\rho - 3p) \quad (23)$$



# Accelerating models

Variable transformation:  $x = \log a$ , which implies that  $\dot{x} = \dot{a}/a = H$ .

$$\frac{d}{dt} = H \frac{d}{dx} \quad \frac{d^2}{dt^2} = \dot{H} \frac{d}{dx} + H^2 \frac{d^2}{dx^2} \quad (21)$$

$$\psi_{xx} + \left( \frac{\dot{H}}{H^2} + 3 \right) \psi_x - \frac{\psi_x^2}{2\psi} + \frac{1}{3H^2} (V_\varphi + V_\psi) = 0; \quad (22)$$

$$\varphi_{xx} + \left( \frac{\dot{H}}{H^2} + 3 \right) \varphi_x - \frac{1}{3H^2} [2V - (\varphi - \psi + 1) V_\varphi - V_\psi] = \frac{\kappa^2}{3H^2} (\rho - 3p) \quad (23)$$

Choosing a potential of the form  $V = V_0 (\varphi - \psi)^2$  implies

$$\psi_{xx} + (2 - q) \psi_x - \frac{\psi_x^2}{2\psi} = 0; \quad (24)$$

$$\varphi_{xx} + (2 - q) \varphi_x = 0. \quad (25)$$

# Accelerating models

Another variable transformation:  $u = \psi_x$  and  $v = \varphi_x$ .

$$\psi_{xx} = u \frac{du}{d\psi} \quad \varphi_{xx} = v \frac{dv}{d\varphi}. \quad (26)$$

The equations simplify to:

$$u \frac{du}{d\psi} + (2 - q) u - \frac{1}{2\psi^2} u^2 = 0; \quad (27)$$

$$v \frac{dv}{d\varphi} + (2 - q) v = 0. \quad (28)$$

# Accelerating models

Another variable transformation:  $u = \psi_x$  and  $v = \varphi_x$ .

$$\psi_{xx} = u \frac{du}{d\psi} \quad \varphi_{xx} = v \frac{dv}{d\varphi}. \quad (26)$$

The equations simplify to:

$$u \frac{du}{d\psi} + (2 - q) u - \frac{1}{2\psi^2} u^2 = 0; \quad (27)$$

$$v \frac{dv}{d\varphi} + (2 - q) v = 0. \quad (28)$$

These equations can be solved for  $\psi(a)$  and  $\varphi(a)$ :

$$\varphi(a) = \frac{C_1}{2 - q} + C_2 a^{q-2} \quad ; \quad \psi(a) = \left[ \frac{a^{q-2} e^{C_4(q-2)} + C_3}{2(2 - q)} \right]^2. \quad (29)$$

# Accelerating models

Solution for the scale factor:

$$-\frac{\dot{H}}{H^2} = \frac{d}{dt} \frac{1}{H} = q + 1 \implies a(t) = C_2 [(q + 1)t + C_1]^{\frac{1}{q+1}} \quad (30)$$

Conditions:

- 1  $a(t = 0) = 0 \implies C_1 = 0$
- 2  $a(t = t_0) = a_0 \implies C_2 = a_0 [(q + 1)t_0]^{-\frac{1}{q+1}}$

# Accelerating models

Solution for the scale factor:

$$-\frac{\dot{H}}{H^2} = \frac{d}{dt} \frac{1}{H} = q + 1 \implies a(t) = C_2 [(q + 1)t + C_1]^{\frac{1}{q+1}} \quad (30)$$

Conditions:

- 1  $a(t = 0) = 0 \implies C_1 = 0$
- 2  $a(t = t_0) = a_0 \implies C_2 = a_0 [(q + 1)t_0]^{-\frac{1}{q+1}}$

The solution for the scale factor is

$$a(t) = a_0 \left( \frac{t}{t_0} \right)^{\frac{1}{q+1}}. \quad (31)$$

In the particular case  $q = -1$  the solution is different

$$\dot{H} = 0 \Leftrightarrow H = H_0 \Leftrightarrow a(t) = a_0 e^{H_0(t-t_0)}. \quad (32)$$

Conditions for the scalar fields:

- 1  $\varphi(a = \infty) = \varphi_\infty$  ;  $\psi(a = \infty) = \psi_\infty$  ;
- 2  $\varphi(a = a_0) = \varphi_0$  ;  $\psi(a = a_0) = \psi_0$  .

Conditions for the scalar fields:

- 1  $\varphi(a = \infty) = \varphi_\infty$  ;  $\psi(a = \infty) = \psi_\infty$  ;
- 2  $\varphi(a = a_0) = \varphi_0$  ;  $\psi(a = a_0) = \psi_0$  .

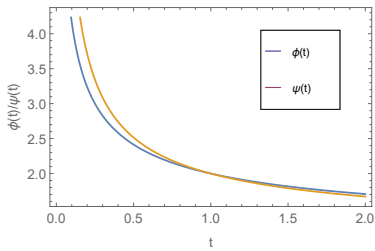
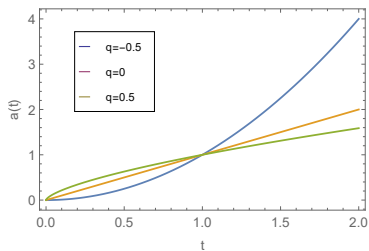
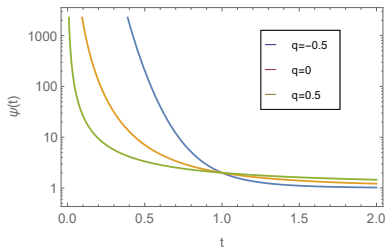
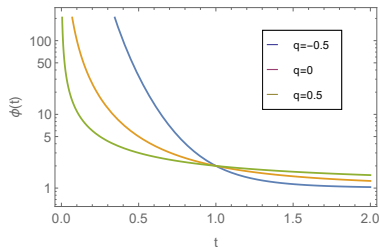
The solutions for the scalar fields become

$$\varphi(a) = \varphi_\infty \left[ 1 + \left( \frac{a}{a_0} \right)^{q-2} \left( \frac{\varphi_0}{\varphi_\infty} - 1 \right) \right] ; \quad (33)$$

$$\psi(a) = \psi_\infty \left[ 1 + \left( \frac{a}{a_0} \right)^{q-2} \left( \sqrt{\frac{\psi_0}{\psi_\infty}} - 1 \right) \right]^2 . \quad (34)$$

This analysis is only valid for  $-1 < q < 2$ .

# Accelerating models













# Conclusions

- Analytical solutions can be obtained in this theory;
- An accelerated expansion rate arises naturally;
- The potential that simplifies the equations has a physical meaning;
- The solutions decrease with an increase in the scale factor;
- More generalizations such as  $R^{\mu\nu} R_{\mu\nu}$  terms can be considered;
- The theory also supports wormhole and black-hole solutions; (work in progress)

# References

-  S. Perlmutter *et al.* *Astrophys. J.* **517**, 565 (1999) [astro-ph/9812133].
-  A. G. Riess *et al.* *Astron. J.* **116**, 1009 (1998) [astro-ph/9805201].
-  E. J. Copeland, M. Sami, and S. Tsujikawa, *Int. J. Mod. Phys. D* **15**, 1753 (2006) [hep-th/0603057].
-  T. Clifton, P. G. Ferreira, A. Padilla, and C. Skordis, *Phys. Rept.* **513**, 1 (2012) [arXiv:1106.2476 [astro-ph.CO]].
-  S. Nojiri and S. D. Odintsov, *Phys. Rept.* **505**, 59 (2011) [arXiv:1011.0544 [gr-qc]].
-  T. Harko, T. S. Koivisto, F. S. N. Lobo, and G. J. Olmo, *Phys. Rev. D* **85**, 084016 (2012) [arXiv:1110.1049 [gr-qc]].
-  S. Capozziello, T. Harko, F. S. N. Lobo, and G. J. Olmo, *Int. J. Mod. Phys. D* **22**, 1342006 (2013) [arXiv:1305.3756 [gr-qc]].
-  N. Tamanini and C. G. Boehmer, *Phys. Rev. D* **87**, 084031 (2013)

Thank you for your attention!